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Short Communication

On the Clifford linearization of Laplacian

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Abstract

In this paper, we shall give a characterization of the differential operator $D = \alpha_0 \partial/\partial x_0 + \alpha_1 \partial/\partial x_1 + \cdots + \alpha_m \partial/\partial x_m$ with coefficients α_i ($i = 0, 1, \dots, m$) of Clifford number for which any solution of the differential equation $Di^2 = 0$ is always a solution of Laplace's equation $Di^2 = 0$, where $A = \partial^2/\partial x_1^2 + \partial^2/\partial x_1^2 + \cdots + \partial x_m^2$.

Key words: Clifford algebra, linearization, Laplacian.

1. Introduction

The Clifford algebra was constructed by W. K. Clifford in 1878 as a generalization of the quaternion algebra. It was studied in the 1930s in connection with the theory of $spinors^{1-4}$ and has been studied in mathematics and physics⁵⁻³⁰.

The generalized Clifford algebra which is a generalization of the ordinary Clifford algebra was constructed as a generalization of the theory of spinors and had extensively been studied by many authors^{10–18}. In 1971, T. Nôno^{17–18} had also generalized the concept of linearization of wave equation for the more general differential equation as another generalization of the theory of spinors.

Many authors have studied higher dimensional function theories^{19–26} as an extension of classical complex function theory. This study has also been applied within a number of areas of theoretical physics (for example, refs 27–29). Most of the function theories^{19–26} associated with the solutions of first order elliptic differential equations are special linearizations of the Laplace's equation.

We gave³⁰ the characterization of the differential operator $D = \alpha_0 \partial/\partial x_0 + \alpha_1 \partial/\partial x_1 + \alpha_2 \partial/\partial x_2 + \alpha_3 \partial/\partial x_3$ with quaternionic coefficients α_i (i=0,1,2,3) for which any solution of the differential equation Du = 0 is always a solution of the Laplace's equation $(\partial^2/\partial x_0^2 + \partial^2/\partial x_1^2 + \partial^2/\partial x_2^2 + \partial^2/\partial x_3^2)u = 0$, where u is a quaternionic function.

In this paper, we shall give a generalization of the result in ref. 30 for Laplacian of (m+1)-real variables $(m \ge 1)$.

2. Preliminaries

Let A_n be the Clifford algebra over an *n*-dimensional vector space with orthogonal basis $\{e_1, e_2, \ldots, e_n\}$. It is well known that A_n is a real 2^n -dimensional associative, but the non-commutative algebra and its basis $\{e_1, e_2, \cdots, e_n, \cdots, e_1e_2\cdots e_n\}$ satisfy the following:

$$e_i e_j + e_j e_i = -2\delta_{ij} \ (i, j = 1, 2, \cdots, n),$$

 e_0 is identity of A_n ,

where δ_{ii} is the Kronecker's delta. Then, every element z in A_n is of the form

$$z = e_0 x_0 + e_1 x_1 + \dots + e_n x_n + e_1 e_2 \cdots e_n x_{12\dots n},$$

where $x_0, x_1, \ldots, x_{12\dots n}$ are real numbers. For two Clifford numbers $z = e_0 x_0 + e_1 x_1 + \cdots + e_n x_n + \cdots + e_1 e_2 \cdots e_n x_{12\dots n}$ and $w = e_0 y_0 + e_1 y_1 + \cdots + e_n y_n + \cdots + e_1 e_2 \cdots e_n y_{12\dots n}$, the inner product (z, w) is defined by the following:

$$(z,w) = x_0y_0 + x_1y_1 + \dots + x_ny_n + \dots + x_{12\dots n}y_{12\dots n},$$

and the norm |z| of z is given by

$$|z| = \sqrt{(z,z)}$$

In this paper, let *m* be an arbitrary integer such that $l \leq m \leq n$. The subspace of A_n spanned by the elements e_0, e_1, \dots, e_m is identified with \mathbb{R}^{m+1} . For each element $z = e_0 x_0 + e_1 x_1 + \dots + e_m x_m$ in \mathbb{R}^{m+1} , the conjugate number z^* and the inverse z^{-1} are given by the following:

$$z^* = e_0 x_0 - \sum_{i=1}^m e_i x_i, \ z^{-1} = \frac{z^*}{|z|^2} \ (z \neq 0).$$

For elements z and w in \mathbb{R}^{m+1} , we obtain

$$|zw| = |z| |w|. \tag{2.1}$$

Let $\partial/\partial x_i$ $(i = 0, 1, \dots, m)$ be the usual real differential operators. We consider the following Clifford differential operator:

$$D = \sum_{i=1}^{m} \alpha_i \frac{\partial}{\partial x_i}, \qquad (2.2)$$

where $\alpha_i = \sum_{j=0}^{m} e_j \alpha_{ij}$ $(i = 0, 1, \dots, m)$ are elements in \mathbf{R}^{m+1} . For the above differential



operator D, the matrix $A = (a_{ij})$ is said to be the *matrix* of D. Also, for the differential operator D of (2.2) we define the conjugate differential operator D^* by

$$D^* = \sum_{i=0}^m \alpha_i^* \frac{\partial}{\partial x_i},$$

where α_i^* is the conjugate number of α_i $(i = 0, 1, \dots, m)$.

Let G be a subset of \mathbb{R}^{m+1} . We consider a function $f(z) = e_0 f_0(z) + e_1 f_1(z) + \dots + e_n f_n(z) + \dots + e_n f_{12\dots n}(z)$ defined in G, where $z = (x_0, x_1, \dots, x_m) \in G$. We say that a differential operator D of (2.2) is a *linearization* of the Laplacian $\Delta = \partial^2 / \partial x_0^2 + \partial^2 / \partial x_1^2 + \dots + \partial^2 / \partial x_m^2$ if and only if any solution of a differential equation

$$Df = 0$$
 (2.3)

is always a solution of Laplace's equation

$$\Delta f = 0.$$
 (2.4)

Remark: If $\alpha_j = 0$ for some *j*, then the differential operator *D* is not a linearization of Laplacian Δ , since Df = 0 but $\Delta f \neq 0$ for a function $f(x_0, x_1, \dots, x_m) = x_j^2$.

3. Main theorem

Let O(m + 1) be the (m+1)-orthogonal group. We need the following two lemmas which are easily proved.

Lemma 1: Let D be a differential operator of (2.2), $A = (a_{ij})$ be the matrix of D. Then, the following conditions (1), (2) and (3) are all equivalent.

(1) $A \in O(m+1)$. (2) $\alpha_i^* \alpha_j + \alpha_j^* \alpha_i = 2\delta_{ij} (i, j = 0, 1, \dots, m)$. (3) $(\alpha_b \ \alpha_j) = \delta_{ij} (i, j = 0, 1, \dots, m)$.

Lemma 2: The functions

 $f_{ij}(x_0, x_1, \dots, x_m) = (\alpha_i^{-1} \alpha_j)^2 x_i^2 - 2(\alpha_i^{-1} \alpha_j) x_i x_j + x_j^2, (i, j = 0, 1, \dots, m)$ are solutions of the differential equation (2.3), where α_i $(i = 0, 1, \dots, m)$ are coefficients of D.

Theorem: Let D be a differential operator of (2.2) and A be the matrix of D. Then, the following conditions (1), (2) and (3) are all equivalent.

(1) D is a linearization of Laplacian Δ . (2) $A = \lambda O$, $O \in O(m+1)$, $(\lambda > 0)$. (3) $D^*D = \lambda^2 \Delta$, $(\lambda > 0)$. **Proof:** We first prove that $(1) \rightarrow (2)$. Let f_{ij} $(i \neq j, i, j = 0, 1, \dots, m)$ be the functions in Lemma 2. Since we have

$$\Delta f_{ij} = 2(\alpha_i^{-1} \alpha_j)^2 + 2,$$

from $\Delta f_{ii} = 0$ it follows that

$$(\alpha_i^{-1}\alpha_j)^2 + 1 = 0 \ (i \neq j, \ i, \ j = 0, \ 1, \cdots, \ m).$$
(3.1)

From (3.1) and remark in Section 2, we obtain

$$\alpha_i^{-1}\alpha_j + \alpha_j^{-1}\alpha_i = 0 \ (i \neq j, \ i, j = 0, 1, \cdots, m).$$

From (3.1), we have $|\alpha_i^{-1}| |\alpha_j| = |\alpha_i^{-1}| |\alpha_i|$ $(i \neq j, i, j = 0, 1, \dots, m)$ which implies $|\alpha_i| = |\alpha_i| > 0$ for all $i, j = 0, 1, \dots, m$. It now easily follows that

$$\alpha_i^* \alpha_j + \alpha_j^* \alpha_i = 0 \ (i \neq j, \quad i, j = 0, 1, \cdots, m). \tag{3.2}$$

Put

$$\lambda = |\alpha_0| = |\alpha_1| = \cdots = |\alpha_m| > 0. \tag{3.3}$$

Thus, (3.2), (3.3) and Lemma 1 show that $A = \lambda O$, $O \in O(m+1)$, $(\lambda > 0)$.

Next, we prove that (2) \rightarrow (3). By operating D^* on the left side of D, from Lemma 1 and condition (2) we have

$$D^*D = \lambda^2 \Delta + \sum_{\substack{i,j = 0 \\ i < i}}^m (\alpha_i^* \alpha_j + \alpha_j^* \alpha_i) \frac{\partial}{\partial x_i} \frac{\partial}{\partial x_j} = \lambda^2 \Delta.$$

At last, we prove that $(3) \rightarrow (1)$. Let f be any solution of Df=0. From condition (3), it follows that $\hat{0}=D^*Df=\lambda^2\Delta f$. Thus, D is a linearization of Laplacian Δ .

Corollary: Let D* be the conjugate differential operator of D and A* be the matrix of D*. Then, the following conditions are all equivalent.

(1) D is a linearization of Laplacian Δ . (2) D^* is a linearization of Laplacian Δ . (3) $A = \lambda O$, $O \in O(m+1)$, $(\lambda > 0)$. (4) $A^* = \lambda O$, $O \epsilon O(m+1)$, $(\lambda > 0)$. (5) $D^*D = \lambda^2 \Delta$, $(\lambda > 0)$. (6) $DD^* = \lambda^2 \Delta$, $(\lambda > 0)$

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