

On points of k th absolute continuity

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Abstract

In this paper we define points of k th absolute continuity of a real function and study their properties including those induced by higher order (approximate) Riemann* derivatives. Also we investigate the structure of the class of all continuous functions having at least one point of k th absolute continuity on an interval $[a, b]$.

Key words: AC_k functions, BV_k functions, AC_k points, (k) singular functions, (approximate) k th Riemann* derivative.

1. Introduction

Russell¹ introduced the concept of functions of bounded k th variation (BV_k functions) and, as a natural consequence, the definition of absolutely k th continuous functions (AC_k functions) was introduced by Das and Lahiri². Extension of these notions on a linear set was made by De Sarkar and Das³. In the generalisations of many results of classical bounded variation and absolute continuity the concept of k th Riemann* derivative is seen to be essentially important. An approximate generalisation of this derivative is the outcome of the introduction of the definition of approximate k th Riemann* derivative by De Sarkar *et al*⁴.

Chakrabarty and Bhakta⁵ defined points of absolute continuity and studied their properties. Šalát⁶ investigated the structure of the metric space $C(a, b)$ of all continuous functions on $[a, b]$ (with sup-metric) from the view point of points of absolute continuity and generalised some results of Chakrabarty and Bhakta⁵ using the notions of approximate derivative, locally (strongly locally) Hölderian and locally (strongly locally) Lipschitzian functions (at a point).

The present authors introduced the definition of points of bounded k th variation in a recent communication⁷. In view of the developments of theories of bounded variation and related absolute continuity and the facts discussed above we propose, in this paper, to define points of k th absolute continuity of a real function and study some of their

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rather interesting properties along with those induced by higher order (approximate) Riemann* derivatives. Also we show that the class of all continuous functions having at least one point of k th absolute continuity on an interval $[a, b]$ is an $F_{\sigma\delta\sigma}$ -set of the first Baire category.

Let f be a real valued function defined on the real line R_1 . Let a, b be two fixed real numbers with $a < b$ and let k be a positive integer greater than 1. The ordinary k th derivative of f at x , $x \in R_1$, denoted by $f^{(k)}(x)$; $f^{(0)}$, stands for f . Let $C(a, b)$ denote the class of all continuous functions on $[a, b]$.

Definition 1.1¹: Let x_0, x_1, \dots, x_k be $(k+1)$ distinct points, not necessarily in the linear order, belonging to R_1 . Then define the k th divided difference of f as

$$Q_k(f; x_0, x_1, \dots, x_k) = \sum_{i=0}^k \left\{ f(x_i) / \prod_{\substack{j=0 \\ j \neq i}}^k (x_i - x_j) \right\}.$$

For the definitions of functions of bounded k th variation (BV_k functions) and k th absolute continuity (AC_k functions) we refer to De Sarkar and Das³.

Definition 1.2⁴: Let x be any point in $[a, b]$ and let x_1, x_2, \dots, x_k be any set of k points in $[a, b]$ with the property $0 < |x_1 - x| < |x_2 - x| < \dots < |x_k - x|$. If the iterated approximate limit

$$\lim_{x_k \rightarrow x} \text{ap} \dots \lim_{x_1 \rightarrow x} \text{ap} k! Q_k(f; x, x_1, \dots, x_k)$$

exists (possibly infinite), then this limit is called the approximate k th Riemann* derivative of f at x and is denoted by $AD^k f(x)$. Replacing the approximate limits by the ordinary limits in this definition we get the definition of k th Riemann* derivative of f at x , as in Russell¹, and we denote it by $D^k f(x)$.

Definition 1.3⁸: A function S which is BV_k on $[a, b]$ is said to be a (k) singular function if S is not a polynomial of degree less than k but $S^{(k)}$ vanishes almost everywhere on $[a, b]$.

We denote by $P^*(f)$, $P(f)$, $L^*(f)$ and $L(f)$, respectively, the set of all such points $p \in (a, b)$ at which f is strongly locally Hölderian, locally Hölderian, strongly locally Lipschitzian and locally Lipschitzian. (For definitions of such functions we refer the reader to Šalát⁶, Beesley *et al*⁹ and Belas and Šalát¹⁰.)

2. AC_k points

Before going into the definition of AC_k points we prove a theorem from which useful inferences can be drawn.

Theorem 2.1: If $AD^{k-1}f$ is absolutely continuous on $[a, b]$, then f is AC_k on $[a, b]$.

Proof: Consider an elementary system

$I(x_{i,1}, \dots, x_{i,k-1}) : (x_{i,0}, x_{i,k}); i = 1, 2, \dots, n$ in $[a, b]$. Then in view of Lemma 4 of Russell¹, we have

$$\sigma |I| = \sum_{i=1}^n |Q_{k-1}(f; x_{i,1}, \dots, x_{i,k}) - Q_{k-1}(f; x_{i,0}, \dots, x_{i,k-1})|.$$

Now by Theorem 8 of De Sarkar *et al*⁴, $AD^{k-1}f$ possesses the mean value property on $[a, b]$, namely, for any set of k points $x_1 < x_2 < \dots < x_k$ in $[a, b]$ there exists at least one η in (x_i, x_k) such that

$$(k-1)! Q_{k-1}(f; x_1, x_2, \dots, x_k) = AD^{k-1}f(\eta).$$

Hence it is easy to see that

$$\sigma |I| = \frac{1}{(k-1)!} \sum_{i=1}^n |AD^{k-1}f(\beta_i) - AD^{k-1}f(\alpha_i)|$$

where $(\alpha_i, \beta_i), i = 1, 2, \dots, n$ is a sequence of non-overlapping intervals in $[a, b]$. The rest of the proof is straightforward.

Definition 2.1: Let x be a point in $[a, b]$. We say that x is a point of k th absolute continuity of f if there exists a closed neighbourhood of x on which f is AC_k . On the other hand, if there exists no closed neighbourhood of x on which f is AC_k , then x is said to be a point of k th nonabsolute continuity of f .

For $k=1$, Definition 2.1 gives the definition of AC points as in Chakrabarty and Bhakta⁵.

A point of k th absolute continuity and a point of k th nonabsolute continuity of f will be called an AC_k point and a NAC_k point of f respectively. We shall denote by $G(f)$ and $N(f)$, respectively, the set of all AC_k points and NAC_k points of f .

It is easy to see that the set $G(f)$ is open in $[a, b]$ and hence $N(f)$ is a closed subset of $[a, b]$.

In view of Corollary 2.4 of De Sarkar and Das³, the preceding Theorem 2.1 and the fact that the existence of $D^k f$ implies that of $AD^k f$ we have the following theorem, the proof of which is omitted.

Theorem 2.2: The point $x \in [a, b]$ is an AC_k point of f if and only if x is an AC_r point of $AD^{k-r}f, r = 1, 2, \dots, k-1$.

Theorem 2.3: If the k th divided difference of f in $[a, b]$ are bounded then each $x \in [a, b]$ is an AC_r point of $AD^{k-r}f, r = 1, 2, \dots, k$.

The proof is omitted.

Theorem 2.4: If $D^{k-1}f$ is continuous and f is BV_k on $[a, b]$, then $N(f)$ is either void or a perfect set.

Proof: The set $N(f)$ is void if f is AC_k on $[a, b]$. Let f be not AC_k on $[a, b]$. Then, by Theorem 3.1 of Das and Lahiri⁸, f can be uniquely expressed in the form $f = \phi + S$ where ϕ is AC_k on $[a, b]$, $\phi^{(r)}(a) = f^{(r)}(a)$, $r = 0, 1, \dots, k-1$ and S is a (k) singular function or an identically zero function. Then clearly, an AC_k point of f is an AC_k point of S and conversely. Let $G(f) = \cup\{(\alpha_i, \beta_i)\}; i = 1, 2, \dots$. If $[\alpha, \beta]$ is any closed subinterval of (α_i, β_i) , then S is AC_k on $[\alpha, \beta]$. Since $S^{(k)}$ vanishes almost everywhere on $[a, b]$, by Theorem 2 of Das and Lahiri², S is a polynomial of degree $(k-1)$ at most. Thus it follows that S is a polynomial of degree $(k-1)$ at most on $[\alpha_i, \beta_i]$. Hence, by Lemma 1 of Russell¹, $S^{(k)}(x) = 0$ for all $x \in G(f)$. The set $N(f)$ is not enumerable, for in that case S becomes a polynomial of degree $(k-1)$ at most in $[a, b]$ which contradicts the fact that S is a (k) singular function. Let $E(f)$ be the set of condensation points of $N(f)$. Then the set $N(f) - E(f) = D(f)$ is at most enumerable. We have $[a, b] = A(f) \cup E(f)$ where $A(f) = D(f) \cup G(f)$ and $E(f) \cap A(f) = \emptyset$ (null set). Since $E(f)$ is closed, the set $A(f)$ is open and contains at most an enumerable set of points of $N(f)$. We take $A(f) = \cup\{(a_i, b_i)\}; i = 1, 2, \dots$, where the intervals (a_i, b_i) are non-overlapping. By Theorem 2.3 of De Sarkar and Das³, $D^{k-1}\phi$ is continuous on (a, b) and hence $D^{k-1}S$ is continuous on (a, b) . Also $D^k S$ vanishes on $[a_i, b_i]$ except on enumerable set of points. Therefore, by Hobson¹¹ (p. 365), $D^{k-1}S$ is constant on $[a_i, b_i]$. So each point of $[a_i, b_i]$ is an AC point of $D^{k-1}S$ and hence by Theorem 2.1, is an AC_k point of S . Therefore, each point of $[a_i, b_i]$ is an AC_k point of f .

Thus $A(f) \subset G(f)$ and so $N(f) = E(f)$. Hence by Theorem 3 of Natanson¹² (p. 53), $N(f)$ is a perfect set. This proves the theorem.

Theorem 2.5: If $D^k f$ exists on (a, b) , then $N(f)$ is a nowhere dense set in $[a, b]$.

Proof: Let C and D denote, respectively, the set of all continuity points and discontinuity points of $D^k f$. Denjoy¹³ proved that if a Peano derivative of some order exists finitely so does the Riemann* derivative of the same order and *vice versa*. Later Oliver¹⁴ showed that the Peano derivative belongs to the first Baire class. Hence $D^k f$ is a function in the first Baire class. Thus the set D is a set of first Baire category in $[a, b]$ (cf. Mukhopadhyay¹⁵, p. 182).

Let x be any point in C . Then $D^k f$ is bounded in a certain neighbourhood of x . Hence by Theorem 3 of Oliver¹⁴, $f^{(k)}$ is bounded in some neighbourhood of x . From this we easily see that $f^{(k-1)}$ satisfies Lipschitzian condition in an interval containing x . Therefore $f^{(k-1)}$ is absolutely continuous and hence (by Theorem 2.1) f is AC_k on a neighbourhood of x and so $x \in G(f)$. Thus $C \subset G(f)$ and so $N(f) \subset D \cup \{a\} \cup \{b\}$.

Since D is a set of first category it thus follows that $N(f)$ is also a set of first category. Since $N(f)$ is closed in $[a, b]$ it must be nowhere dense. This completes the proof.

Since the existence of the k th Riemann* derivative implies that of approximate k th Riemann* derivative we produce a generalisation of the above theorem as follows:

Theorem 2.6: If $AD^k f$ exists on (a, b) , then $N(f)$ is a nowhere dense set in $[a, b]$.

Proof: Let C and D denote, respectively, the set of all continuity points and discontinuity points of $AD^k f$. Since, by Theorem 2.6 of De Sarkar *et al*⁴, $AD^k f$ is a function in the first

Baire class, the set D is a set of first Baire category in $[a, b]$. Let $x \in C$. Then there exists an interval $I = [x - \delta, x + \delta] \subset [a, b]$ such that $AD^k f$ is bounded on I . Therefore there exists a $K > 0$ such that $|AD^k f(\eta)| \leq K$ for all $\eta \in I$.

Let α, β be any two points in I . We consider the set of $2k$ points $\alpha < \alpha_1 < \alpha_2 < \dots < \alpha_{k-1} < \beta_{k-1} < \dots < \beta_1 < \beta$ in I . We relabel the set of points as

$$z_0 < z_1 < z_2 < \dots < z_{k-1} < z_k < z_{k+1} < \dots < z_{2k-2} < z_{2k-1}$$

where $z_0 = \alpha$, $z_{2k-1} = \beta$, $z_i = \alpha_i$; $i = 1, 2, \dots, k-1$ and $z_i = \beta_{2k-1-i}$,

$i = k, k+1, \dots, 2k-2$. Then we have, using Lemma 4 of Russell¹,

$$\begin{aligned} & |Q_{k-1}(f; z_0, z_1, \dots, z_{k-1}) - Q_{k-1}(f; z_k, \dots, z_{2k-1})| \\ & \leq \sum_{i=0}^{k-1} |Q_{k-1}(f; z_i, \dots, z_{i+k-1}) - Q_{k-1}(f; z_{i+1}, \dots, z_{i+k})| \\ & = \sum_{i=0}^{k-1} |z_i - z_{i+k}| |Q_k(f; z_i, \dots, z_{i+k})|. \end{aligned}$$

Hence, by Theorem 8 (Mean value theorem) of De Sarkar *et al*⁴, we get

$$\begin{aligned} & |Q_{k-1}(f; \alpha, \alpha_1, \dots, \alpha_{k-1}) - Q_{k-1}(f; \beta_{k-1}, \dots, \beta_1, \beta)| \\ & \leq \sum_{i=0}^{k-1} |z_i - z_{i+k}| |AD^k f(\eta_i)| / k!, \quad \eta_i \in (z_i, z_{i+k}), \\ & \leq K |\alpha - \beta| / (k-1)! \end{aligned}$$

Since the existence of $AD^k f$ implies that of $AD^r f$, $1 \leq r < k$, it is now easy to see that

$$|AD^{k-1} f(\alpha) - AD^{k-1} f(\beta)| \leq K |\alpha - \beta| / (k-1)!$$

Hence $AD^{k-1} f$ is Lipschitzian on I , and so, by Theorem 2.1, $C \subset G(f)$. For the rest of the proof we proceed similarly as in the proof of Theorem 2.5.

From Theorem 2.6 we can easily deduce the following result.

Theorem 2.7: If $AD^k f$ exists on (a, b) , then the set $[a, b] - L^*(AD^{k-1} f)$ is a nowhere dense set in $[a, b]$.

Since $P^*(f) \subset P(f)$, $L(f) \subset P(f)$ and $L^*(f) \subset P^*(f)$ we have

Corollary 2.1: If $AD^k f$ exists on (a, b) , then each of the sets $[a, b] - L(AD^{k-1} f)$, $[a, b] - P^*(AD^{k-1} f)$, $[a, b] - P(AD^{k-1} f)$ is a nowhere dense set in $[a, b]$.

We set

$$A(a, b) = \{f \in C(a, b) / G(f) \text{ is nonvoid}\}$$

and

$$B(a, b) = \{f \in C(a, b) / N(f) = [a, b]\}$$

Then we have $B(a, b) = C(a, b) - A(a, b)$.

We now prove the following theorem.

Theorem 2.8: The class $A(a,b) \subset C(a,b)$ is an $F_{\sigma\delta\sigma}$ -set of the first Baire category in $C(a,b)$.

Proof: Let R^0 be the set of all rational numbers of the interval (a,b) . Let $q \in R^0$, $\delta > 0$, $\varepsilon > 0$, $\eta > 0$. We denote by $A(q,\delta,\varepsilon,\eta)$ the class of all such functions $f \in C(a,b)$ for which the following holds:

If $I(x_{i,1}, \dots, x_{i,k-1}) : (x_{i,0}, x_{i,k})$; $i = 1, 2, \dots, n$ is an elementary system in $[q - \delta, q + \delta]$, $ml = \sum_{i=1}^n (x_{i,k} - x_{i,0}) \leq \eta$, then $\sigma|I| \leq \varepsilon$.

We shall show that $A(q,\delta,\varepsilon,\eta)$ is a closed subset of $C(a,b)$.

Let $f_m \in A(q, \delta, \varepsilon, \eta)$; $m = 1, 2, \dots$, let the sequence $\{f_m\}$ converge to a function f in $C(a,b)$. We shall show that $f \in A(q, \delta, \varepsilon, \eta)$.

Let $I(x_{i,1}, \dots, x_{i,k-1}) : (x_{i,0}, x_{i,k})$; $i = 1, 2, \dots, n$ be an elementary system in $[q - \delta, q + \delta]$ with $ml \leq \eta$. Since f_m and f are uniformly continuous in $[a, b]$, by a simple manipulation, it can be shown that for each set of k points x_0, x_1, \dots, x_{k-1} in $[a, b]$ and an arbitrarily chosen $\nu > 0$, we have for m sufficiently large

$$|Q_{k-1}(f_m; x_0, x_1, \dots, x_{k-1}) - Q_{k-1}(f; x_0, x_1, \dots, x_{k-1})| < \varepsilon/2\nu n. \quad (1)$$

Now, using Lemma 4 of Russell¹,

$$\begin{aligned} \sigma|I| &= \sum_{i=1}^n |Q_{k-1}(f; x_{i,1}, \dots, x_{i,k}) - Q_{k-1}(f; x_{i,0}, \dots, x_{i,k-1})| \\ &\leq \sum_{i=1}^n |Q_{k-1}(f; x_{i,1}, \dots, x_{i,k}) - Q_{k-1}(f_m; x_{i,1}, \dots, x_{i,k})| \\ &\quad + \sum_{i=1}^n |Q_{k-1}(f_m; x_{i,1}, \dots, x_{i,k}) - Q_{k-1}(f_m; x_{i,0}, \dots, x_{i,k-1})| \\ &\quad + \sum_{i=1}^n |Q_{k-1}(f_m; x_{i,0}, \dots, x_{i,k-1}) - Q_{k-1}(f; x_{i,0}, \dots, x_{i,k-1})| \end{aligned}$$

Hence from (1) and (2) and the fact that $f_m \in A(q, \delta, \varepsilon, \eta)$

$$\sigma|I| \leq \varepsilon(1 + 1/\nu).$$

Since $\nu > 0$ is arbitrary, making $\nu \rightarrow \infty$ we get $\sigma|I| \leq \varepsilon$. Hence $f \in A(q, \delta, \varepsilon, \eta)$ and so the set $A(q, \delta, \varepsilon, \eta)$ is closed. Also we see that

$$A(q, 1/\alpha) = \bigcap_{\beta=1}^{\infty} \bigcup_{\gamma=1}^{\infty} A(q, 1/\alpha, 1/\beta, 1/\gamma)$$

and so $A(q, 1/\alpha)$ is an $F_{\sigma\delta}$ -set in $C(a,b)$. Again

$$A(q) = \bigcup_{\alpha=1}^{\infty} A(q, 1/\alpha)$$

and is therefore an $F_{\sigma\delta\sigma}$ -set in $C(a,b)$. Since we have

$$A(a,b) = \bigcup_{q \in R^{\circ}} A(q)$$

it follows, in view of the countability of R° , that the set $A(a,b)$ is an $F_{\sigma\delta\sigma}$ -set in $C(a,b)$.

Further, if $f \in A(a,b)$, then by Corollary 2.4 of De Sarkar and Das³ and Theorem 2.2, $AD^{k-1}f$ is absolutely continuous on a certain interval $I \subset (a,b)$ and $AD^k f$ exists almost everywhere on I . Hence in view of Theorem 2.1, it follows that $A(a,b)$ is a subset H of all such functions from $C(a,b)$ which have at least at one point of (a,b) a finite derivative. Since H is a set of first Baire category (by Hewitt and Stromberg¹⁶, p. 260) the theorem follows.

Corollary 2.2: The set $B(a,b) \subset C(a,b)$ is a $G_{\delta\sigma\delta}$ -set residual in $C(a,b)$.

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